

Modelling the interactions between a cloud of particles and a viscous fluid

Collective behavior of particles in fluids
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Matthieu Hillairet
(IUF & Univ. Montpellier)



Context

Issue :

To derive "macroscopic" models for the interactions between a viscous fluid and many "small" particles

Examples :

- ▶ (Navier)-Stokes+Vlasov

equations :

Hamdache, '98

Boudin *et al* '09,

$$\left\{ \begin{array}{l} \partial_t f + v \cdot \nabla_x f + 6\pi \operatorname{div}_v [(u - v)f] = 0 \\ \rho_f (\partial_t u + u \cdot \nabla_x u) - \Delta_x u + \nabla_x p = -6\pi \int_{\mathbb{R}^3} f(u - v) dv \\ \operatorname{div}_x u = 0 \end{array} \right.$$

- ▶ Sedimentation model :

R. Höfer & R. Schubert '20

$$\left\{ \begin{array}{l} -\operatorname{div} ([2 + 5\phi\rho]D(u) + p\mathbb{I}) = \rho g \\ \operatorname{div} u = 0 \\ \partial_t \rho + u \cdot \nabla \rho = 0 \end{array} \right.$$

Main principle

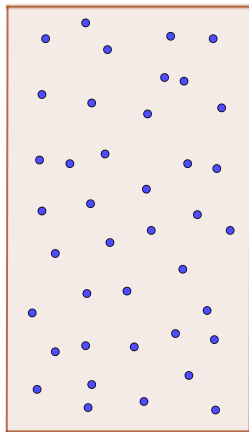


FIGURE – Flow with particles

► Navier-Stokes equations

$$\begin{cases} \partial_t u + u \cdot \nabla u = \operatorname{div} \Sigma(u, p) \\ \operatorname{div} u = 0 \end{cases} \quad \text{in } \mathbb{R}^3 \setminus \bigcup_{i=1}^N B_i(t)$$

$$\begin{cases} u|_{B_i} = V_i + \omega_i \times (x - x_i) \\ u|_{\infty} = Ax \end{cases}$$

► Particle dynamics $B_i = B(x_i, R_N)$

$$\dot{x}_i = V_i$$

$$m_N \ddot{x}_i = - \int_{\partial B_i} \Sigma(u, p) n d\sigma + F$$

$$J_N \dot{\omega}_i = - \int_{\partial B_i} (x - x_i) \times \Sigma(u, p) n d\sigma$$

$$\Sigma(u, p) = \mu(\nabla u + \nabla^\top u) - p\mathbb{I}_3 = 2\mu D(u) - p\mathbb{I}_3.$$

Two crucial phenomena

1 - Stokes drag

Proposition. $\exists!$ classical solution $(U_R[\delta V] + V_\infty, P_R[\delta V])$ to :

$$\begin{cases} -\Delta u + \nabla p = 0, & \text{in } \mathbb{R}^3 \setminus B(0, R) \\ \operatorname{div} u = 0, & \text{in } \mathbb{R}^3 \setminus B(0, R) \end{cases} \quad \begin{cases} u = V_\infty + \delta V, & \text{on } B(0, R) \\ u = V_\infty, & \text{at infinity} \end{cases}$$

Applications.

- ▶ Computation of forces and torques :

$$\int_{\partial B(0, R)} \Sigma(u, p) n d\sigma = 6\pi R \delta V, \quad \int_{\partial B(0, R)} y \times \Sigma(u, p) n d\sigma = 0.$$

- ▶ Extended weak-formulation

$$2 \int_{\mathbb{R}^3} D(u) : D(w) = 6\pi R \delta V \cdot w(0) + O(R^2)$$

for arbitrary divergence free $w \in C_c^\infty(\mathbb{R}^3)$

Two crucial phenomena

2 - Volumic rigidity

Proposition. Given a trace-free $A \in \mathcal{M}_3(\mathbb{R})$, there exists a unique classical solution to

$$\begin{cases} -\Delta u + \nabla p = 0, & \text{in } \mathbb{R}^3 \setminus B(0, R) \\ \operatorname{div} u = 0, & \text{in } \mathbb{R}^3 \setminus B(0, R) \end{cases} \quad \begin{cases} u = V, & \text{on } B(0, R) \\ u = Ax, & \text{at infinity} \end{cases}$$

with :

$$\int_{\partial B(0, R)} \Sigma(u, p) n d\sigma = 0.$$

Applications.

- ▶ Computation of strain/torque :

$$\int_{\partial B(0, R)} y \otimes \Sigma(u, p) n d\sigma = \frac{20\pi}{3} R^3 D(A) + 8\pi R^3 S(A)$$

- ▶ Extended weak formulation

$$2 \int_{\mathbb{R}^3} D(u) : D(w) = \frac{20\pi}{3} R^3 D(A) : \nabla w(0) + 8\pi R^3 S(A) : \nabla w(0) + O(R^4)$$

for arbitrary divergence free $w \in C_c^\infty(\mathbb{R}^3)$

On the discrete problem

Reminder

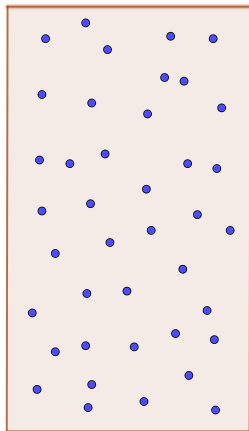


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► Navier-Stokes equations

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$$\Sigma(u, p) = \mu(\nabla u + \nabla^\top u) - p\mathbb{I}_3 = 2\mu D(u) - p\mathbb{I}_3.$$

References

Lagrangian approach

- ▶ Local-in-time existence and uniqueness of classical solutions [C. Grandmont & Y. Maday '98, M.D. Gunzburger, H.-C. Lee & G. A. Seregin '00]
- ▶ Existence and uniqueness of classical solutions up to contact between bodies [T. Takahashi '03; M. Tucsnak & T. Takahashi '04]

Eulerian approach

- ▶ Existence of weak solutions
 - ▶ up to contact between rigid bodies [B. Desjardins & M. Esteban 99; B. Desjardins & M. Esteban, '00]
 - ▶ Global-in-time (2D and 3D) [K.H. Hoffmann & V. Starovoitov '99; J. A. San Martin, V. Starovoitov & M. Tucsnak '02; E. Feireisl '03]
- ▶ Uniqueness of weak solutions [O. Glass & F. Sueur '13; V. Starovoitov '05]

Contact issue

- ▶ Blow-up of solutions [V. Starovoitov '03]
- ▶ Existence of finite-time contact [M.H. '07; M.H. & T. Takahashi '09'10'20; D. Gérard-Varet & M.H. '10'15; L. Sabbagh '19; S. Filippas & A. Tersenov '21]

Distance estimate

Simplified model

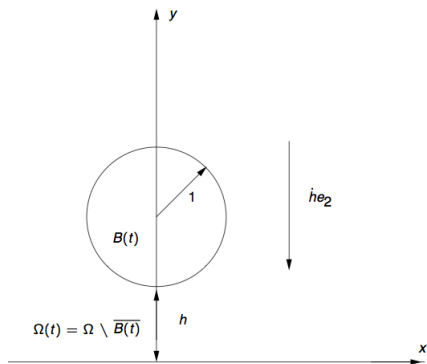


Figure 3. Symmetric configuration

Reduced system

$$\left. \begin{aligned} \mu \Delta u_f - \nabla p_f &= 0 \\ \operatorname{div} u_f &= 0 \end{aligned} \right\} \text{ in } \Omega(t)$$

$$u_f = 0 \text{ on } \partial\Omega$$

$$u_f = \dot{h} e_2 \text{ on } \partial B(t)$$

$$m\ddot{h} = - \int_{\partial B(t)} \Sigma n d\sigma \cdot e_2$$

References

- ▶ Lubrication approximation
[R.G. Cox '67, H.G. Leal '07]
- ▶ Explicit computations
[M. Cooley & M. O'Neill '69]

Analysis of the drag

$$\implies m\ddot{h} = -\mu K \frac{\dot{h}}{h^{\frac{3}{2}}}$$

Alternative Computation of the drag

[M.H., A. Lozinski, M. Szopos, '11 ; D. Gérard-Varet & M.H. '12]

Lemma. Let $h > 0$ and denote $B^h = B((0, 1 + h), 1)$.

The "unique" pair $(w, q) \in H^2(\mathbb{R}_+^2 \setminus \overline{B^h}) \times H^1(\mathbb{R}_+^2 \setminus \overline{B^h})$ solution to :

$$\begin{cases} \mu \Delta w - \nabla q = 0 \\ \nabla \cdot w = 0 \end{cases} \text{ in } \Omega \setminus \overline{B^h}, \quad \begin{cases} w|_{\partial\Omega} = 0 \\ w|_{\partial B^h} = e_2 \end{cases}$$

is characterised by :

$$E[w] = \operatorname{argmin} \left\{ \int_{\mathbb{R}_+^2} |D(u)|^2, u \in C_c^\infty(\mathbb{R}_+^2) \text{ with } \operatorname{div} u = 0 \text{ and } u|_{B^h} = e_2 \right\}.$$

Moreover :

$$\int_{\partial B^h} \Sigma(w, q) n d\sigma \cdot e_2 = 2\mu \int_{\Omega \setminus \overline{B^h}} |D(w)|^2.$$

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Moreover :

$$\int_{\partial B^h} \Sigma(w, q) n d\sigma \cdot e_2 = 2\mu \int_{\Omega \setminus \overline{B^h}} |D(w)|^2.$$

Analysis of the drag

[D.G rard-Varet & M.H. '12]

Application

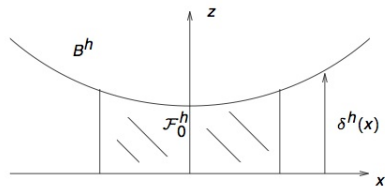


FIGURE – Geometry of the gap

Any $u \in Y_h$ reads $u = \nabla^\perp \phi$ with :

$$(BC_\phi) \quad \begin{cases} \phi(x, \delta_h(x)) = x + C, \\ \phi(x, 0) = 0 \end{cases} \quad \forall x$$

Energy to minimize :

$$\mathcal{E}_h := \mu \int_{\mathcal{F}^h} |\nabla u(x, y)|^2 dx dy$$

Reduced functional :

$$\tilde{Y}_h := \left\{ \phi \in C^\infty(\bar{\mathcal{F}}_0^h) \text{ s.t. } (BC_\phi) \right\} \quad \tilde{\mathcal{E}}_h := \mu \int_{\mathcal{F}_0^h} |\partial_{22} \phi(x, y)|^2 dx dy$$

Remark : Extension to the 3D case [M.H. & T. Kelai '15]

Analysis of the drag

[D.Gérard-Varet & M.H. '12]

Application

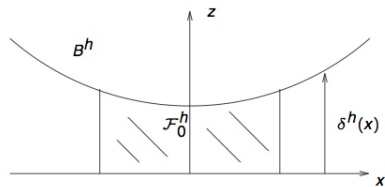


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$$(BC_\phi) \quad \begin{cases} \phi(x, \delta_h(x)) = x + C, \\ \phi(x, 0) = 0 \end{cases} \quad \forall x$$

Energy to minimize :

$$\mathcal{E}_h \geq \mu \int_{\mathcal{F}_0^h} |\nabla^2 \phi(x, y)|^2 dx dy$$

Reduced functional :

$$\tilde{Y}_h := \left\{ \phi \in C^\infty(\bar{\mathcal{F}}_0^h) \text{ s.t. } (BC_\phi) \right\} \quad \tilde{\mathcal{E}}_h := \mu \int_{\mathcal{F}_0^h} |\partial_{22} \phi(x, y)|^2 dx dy$$

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Extensions

Other boundary conditions and 3D case

- ▶ Navier wall laws [D. Gérard-Varet, M.H., C. Wang '15]
- ▶ Tresca boundary conditions [M.H. & T. Takahashi '20]

Other fluid models

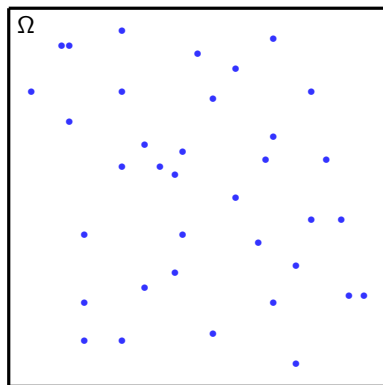
- ▶ Inviscid fluids
[A. Munnier & J.G Houot '08, A. Munnier & K. Ramdani '15, M.H., D. Seck & L. Sokhna '18, D. Coutand '19,]
- ▶ Non-newtonian fluids [E. Feireisl, M.H., S. Nečasová '08]

Multi-body problems [M.H. & T. Takahashi '10, L. Sabbagh '19]

On the asymptotics $N \rightarrow \infty$

Stokes problem in a perforated domain

Brinkman problem



A N -obstacle configuration

Geometrical data :

$$N \in \mathbb{N}, \quad |h_i - h_j| > 10R,$$

$$\mathcal{F} = \mathbb{R}^3 \setminus \bigcup_{i=1}^N \overline{B(h_i, R)}$$

$$(h_1, \dots, h_N) \in [\mathbb{R}^3]^N$$

Problem to be solved :

$$\begin{cases} -\Delta u + \nabla p = 0, & \text{in } \mathcal{F} \\ \operatorname{div} u = 0, & \text{in } \mathcal{F} \end{cases}$$

$$\begin{cases} u = v_i, & \text{on } \partial B_i \\ \lim_{|x| \rightarrow \infty} u(x) = 0. \end{cases}$$

Results

Brinkman problem

Still particles ($v_i = 0 \quad \forall i$)

Rubinstein '86,
Allaire '90,
Höfer-Velázquez '18,
Gérard-Varet '19,
Giunti-Höfer '19,
Höfer-Jansen '20,

"Moving" particles ($(v_i)_{i=1,\dots,N}$ given)

H. Brinkman '47,
J. Luke '89,
L. Desvillettes-F. Golse-V. Ricci '08,
M.H.-A. Mecherbet '20,
M.H. '18,
M.H.-A. Moussa-F. Sueur '19,
K. Carrapatoso-M.H. '20

Example of result

Reference

Theorem [L. Desvillettes, F. Golse & V. Ricci '08]

Consider the case :

(H0) $N \rightarrow \infty$ with $R = 1/N$.

Assume further that :

(H1) $d_{min} = \min \{ \text{dist}(h_i, h_j), \text{dist}(h_i, \partial\Omega) \}$ satisfies $d_{min} \geq 2/N^{\frac{1}{3}}$.

(H2) we have the uniform bound :

$$\frac{1}{N} \sum_{i=1}^N |v_i|^2 \leq C_0$$

(H3) the sequence of empirical measures converges :

$$\frac{1}{N} \sum_{i=1}^N \delta_{h_i} \rightharpoonup \rho(x) dx \in L^\infty \quad \frac{1}{N} \sum_{i=1}^N v_i \delta_{h_i} \rightharpoonup j(x) dx \in L^2.$$

Then $u \rightharpoonup \bar{u}$ in $H_0^1(\Omega)$ – w sol. to :

$$\begin{cases} -\Delta \bar{u} + \nabla \bar{p} &= 6\pi(j - \rho \bar{u}), \\ \text{div} \bar{u} &= 0 \end{cases} \quad \text{on } \Omega$$

Example of result

Improvement

Theorem [M.H. '18]

Consider that (H0), (H2) and (H3) hold true.

Assume further that :

(H'1) $d_{min} \gg 1/N$

(H"1) we can choose $\lambda \ll \min(|d_{min}|^{1/3}, N^{-1/6})$ such that :

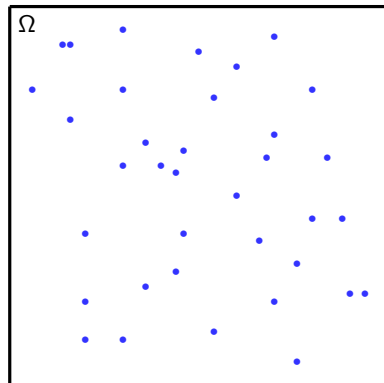
$$\frac{1}{N|\lambda|^3} \sup_{x \in \Omega} \# \{j, h_i \in B(x, \lambda)\} \text{ bounded.}$$

Then $u \rightharpoonup \bar{u}$ in $H_0^1(\Omega)$ – w solution to :

$$\begin{cases} -\Delta \bar{u} + \nabla \bar{p} & = 6\pi(j - \rho \bar{u}), \\ \operatorname{div} \bar{u} & = 0 \end{cases} \quad \text{on } \Omega$$

Stokes problem in a perforated domain

Einstein problem



A N -obstacle configuration

Geometrical data :

$$N \in \mathbb{N}, \quad |h_i - h_j| > 10R,$$

$$\mathcal{F} = \mathbb{R}^3 \setminus \bigcup_{i=1}^N \overline{B(h_i, R)}$$

$$(h_1, \dots, h_N) \in [\mathbb{R}^3]^N$$

Problem to be solved :

$$\begin{cases} -\Delta u + \nabla p = 0, & \text{in } \mathcal{F} \\ \operatorname{div} u = 0, & \text{in } \mathcal{F} \end{cases}$$

$$\begin{cases} u = V_i + \omega_i \times (x - h_i), & \text{on } \partial B_i \\ \int_{\partial B_i} (x - h_i) \times \Sigma(u, p) n d\sigma = 0 \\ \int_{\partial B_i} \Sigma(u, p) n d\sigma = 0. \end{cases}$$

$$\lim_{|x| \rightarrow \infty} |u(x) - Ax| = 0.$$

References

Einstein problem

Computation of first order correction in $\phi \sim NR^3$

Einstein '06

Sánchez-Palencia '85

Haines & Mazzucatto '12

Niethammer & Schubert '20, M.H.-Wu '20

Gérard-Varet '19

Gérard-Varet & Höfer '20

Keller & Rubinfeld '67

Almog & Brenner '03

Computation of next orders (mostly second order)

Periodic case

Saito '50

Zuzovsky, Adler & Brenner '83

Nunan & Keller '84

Ammari, Garapon, Kang & Lee '12

Random case

Batchelor & Green '72, Hinch '77

Gérard-Varet & M.H. '20

Gérard-Varet '20

Gérard-Varet & A. Mecherbet '20

Duerinckx-Gloria '20, Duerinckx '20

Example of result

Theorem [M.H. & D. Wu '20]

Let $K \in \mathbb{R}^3$ and assume :

(A0) $B_i \subset K$ for $i = 1, \dots, N$ and $d_{\min} := \min_{i \neq j} |h_i - h_j| > 4R$

There exists $\varepsilon_0 > 0$ such that :

(A1) $R^3/d^3 < \varepsilon_0$

(A2) $\phi \in L^\infty(K)$ satisfies $\|\phi\|_{L^\infty(K)} < \varepsilon_0$

Denoting $u_c \in Ax + \dot{H}^1(\mathbb{R}^3)$ the unique weak solution to :

$$\begin{cases} -\operatorname{div}((2 + 5\phi)D(u_c)) + \nabla p = 0 \\ \operatorname{div} u = 0 \\ \lim_{|x| \rightarrow \infty} |u_c(x) - Ax| = 0 \end{cases}$$

and $\phi_d = \sum_{i=1}^N \mathbf{1}_{B_i}$, there holds :

$$\|u - u_c\|_{L^p_{loc}} \lesssim |A| [\|\phi_d - \phi\|_{\dot{H}^{-1}(\mathbb{R}^3)} + \left(\frac{R^3}{d^3}\right)^{1+} + \|\phi\|_{L^\infty(K)}^2] \quad \forall p < 3/2.$$

Key steps in the proof – Brinkman case

[M.H. '18]

- ▶ $u^N \rightharpoonup \bar{u}$ in $H_0^1(\Omega) - w$.

$$\begin{aligned}\bar{\mathcal{L}}[w] &:= \int_{\Omega} D(\bar{u}) : D(w) \quad (w \in C_c^\infty(\Omega) \text{ s.t. } \operatorname{div} w = 0) \\ &= \lim_{N \rightarrow \infty} \mathcal{L}^N[w]\end{aligned}$$

- ▶ $(T_k^N)_{k \in \mathcal{K}^N}$ partition of Ω with cubes of width λ_N

$$\mathcal{L}^N[w] = \sum_{k \in \mathcal{K}^N} \int_{T_k^N} D(u^N) : D(\tilde{w}_k) + \operatorname{err}^N$$

where :

$$\tilde{w}_k = \sum_{i | h_i \in T_k^N} U_R[w(h_i)](x - h_i)$$

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$$\mathcal{L}^N[w] = \sum_{k \in \mathcal{K}^N} \left(\sum_{i|h_i \in T_k^N} \frac{6\pi}{N} w(h_i) \cdot \nu_i - \int_{\partial T_k^N} \Sigma(\tilde{w}_k, \tilde{p}_k) \cdot u^N d\sigma \right) + \operatorname{err}^N$$

where :

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- ▶ $(T_k^N)_{k \in \mathcal{K}^N}$ partition of Ω with cubes of width λ_N

$$\mathcal{L}^N[w] = \sum_{k \in \mathcal{K}^N} \left(\frac{1}{N} \sum_{i|h_i \in T_k^N} 6\pi w(h_i) \cdot V_i - \frac{1}{N|T_k^N|} \int_{T_k^N} u^N \cdot \sum_{i|h_i \in T_k^N} 6\pi w(h_i) \right) + \widetilde{\text{err}}^N$$

where :

$$\tilde{w}_k = \sum_{i|h_i \in T_k^N} U_R[w(h_i)](x - h_i)$$

- ▶ Finally :

$$\bar{\mathcal{L}}[w] = 6\pi \left(\int_{\Omega} j \cdot w - \int_{\Omega} \rho \bar{u} \cdot w \right)$$

Thank you for your attention