

Derivation of sedimentation models as a mean-field limit and analysis of the transport-Stokes model

Collective behavior of particles in fluids

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Outline

1 On mean-field limits

2 On the sedimentation of a falling droplet

- Global existence and uniqueness result for (TS)
- Evolution of the surface of the droplet
- Investigation of the spherical shape case

Microscopic model for inertialess sedimentation

n particles B_i centered in x_i with orientation θ_i and radius $R = \frac{r_0}{n}$, $1 \leq i \leq n$

$$\begin{cases} -\Delta u + \nabla p = 0, \operatorname{div}(u) = 0, & \text{on } \mathbb{R}^3 \setminus \bigcup_{i=1}^n \bar{B}_i \\ u = u_i + \omega_i \times (x - x_i), & \text{on } B_i, 1 \leq i \leq n, \\ \lim_{|x| \rightarrow \infty} |u(x)| = 0. & \end{cases}$$

$$\int_{\partial B_i} \Sigma(u, p) \nu d\sigma(x) + \frac{4}{3} \pi r^3 (\rho_p - \rho_f) g = 0, \quad \int_{\partial B_i} (x - x_i) \times [\Sigma(u, p) \nu] d\sigma(x) = 0,$$

$$\dot{x}_i = u_i, \quad \dot{\theta}_i = \omega_i.$$

System of interacting spherical particles

As long as $d_{\min} \geq \frac{c}{n}$ and (roughly) $r_0 = Rn$ small enough we have

$$\dot{x}_i = \kappa g + \frac{6\pi r_0}{n} \sum_{j \neq i} \Phi(x_i - x_j) \kappa g + O(d_{\min})$$

- $\Phi(x) = \frac{1}{8\pi} \left(\frac{I}{|x|} + \frac{x \otimes x}{|x|^3} \right)$ the Oseen tensor
- $\kappa g = \frac{2}{9} R^2 (\rho_p - \rho_f) g$ the velocity fall of one single spherical particle in a Stokes flow

- P. E. Jabin and F. Otto (2004). R. M. Höfer (2018). A. M (2019). R. M. Höfer and R. Schubert (2020).

Propagation of the infinite Wasserstein distance and the minimal inter-particle distance

$$\mathcal{K}^n \rho^n(x) = 6\pi r_0 \int_{\mathbb{R}^3} \chi \Phi(x - y) \kappa g \rho^n(dy), \quad \mathcal{K} \rho(x) = 6\pi r_0 \int_{\mathbb{R}^3} \Phi(x - y) \kappa g \rho(dy)$$

with $\rho^n = \frac{1}{n} \sum_i \delta_{x_i}$, formally we have

$$\begin{aligned} \frac{d}{dt} W_\infty(\rho^n, \rho) &\lesssim \|\mathcal{K}^n \rho^n - \mathcal{K} \rho\|_\infty, \quad \frac{d}{dt} d_{\min} \lesssim d_{\min} \|\nabla \mathcal{K}^n \rho^n\|_\infty \\ \|\mathcal{K}^n \rho^n - \mathcal{K} \rho\|_\infty &\lesssim W_\infty \left(1 + W_\infty + \frac{W_\infty^2}{d_{\min}} \right), \quad \|\nabla \mathcal{K}^n \rho^n\|_\infty \lesssim \left(1 + \frac{W_\infty^3}{d_{\min}^2} \right) \end{aligned}$$

Cluster configuration

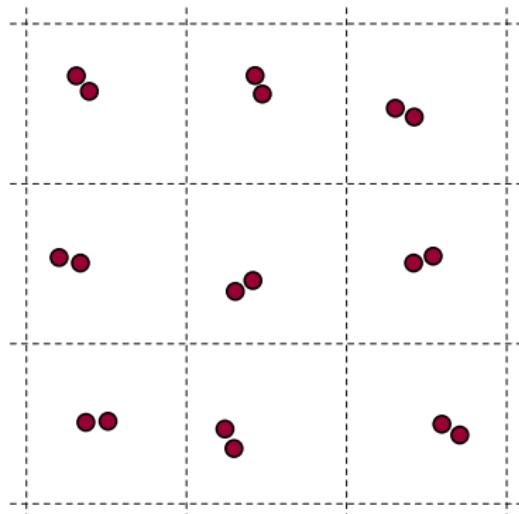
As a first step for rigorous justification of polymeric suspensions

n pairs of spheres centered in x_1^i, x_2^i

$$|x_1^i - x_2^i| \sim R, 1 \leq i \leq n.$$

$x_+^i := \frac{x_1^i + x_2^i}{2}$ center of the i^{th} cluster

$\xi^i := \frac{x_1^i - x_2^i}{2R}$ orientation of the i^{th} cluster



- C. Le Bris, T. Lelièvre. Micro-macro models for viscoelastic fluids: modelling, mathematics and numerics 2011.

System of interacting clusters

As long as $d_{\min} \geq \frac{c}{\sqrt{n}}$ and r_0 small enough we have

$$\begin{aligned}\dot{x}_+^i &= (\mathbb{A}(\xi_i))^{-1} \kappa g + \frac{6\pi r_0}{n} \sum_{j \neq i} \Phi(x_+^i - x_+^j) \kappa g + O(d_{\min}) \\ \dot{\xi}_i &= \left(\frac{6\pi r_0}{n} \sum_{j \neq i} \nabla \Phi(x_+^i - x_+^j) \kappa g \right) \cdot \xi_i + O(d_{\min})\end{aligned}$$

- $(\mathbb{A}(\xi_i))^{-1} \kappa g$ the mean velocity fall of one pair of identical spheres in a Stokes flow

- D.J. Jeffrey and Y. Onishi, Calculation of the resistance and mobility functions for two unequal spheres in low-Reynolds-number flow. J. Fluid Mech. 139 (1984) 261–290.
- A. M. A model for suspension of clusters of particle pairs. 2019. hal-02171615. To appear in ESAIM: Mathematical Modelling and Numerical Analysis.

System of interacting axisymmetric particles

In the case where the shape has 3 axes of symmetry the system obtained is

$$\dot{x}_i \sim (\mathcal{M}_1(\xi_i)) \kappa g + \frac{6\pi r_0}{n} \sum_{j \neq i} \Phi(x_+^i - x_+^j) \kappa g$$

$$\dot{\xi}_i \sim \mathcal{M}_2(\xi_i) \left(\frac{6\pi r_0}{n} \sum_{j \neq i} \nabla \Phi(x_+^i - x_+^j) \kappa g \cdot \xi_i \right)$$

- $(\mathcal{M}_1(\xi_i)) \kappa g$ the velocity fall of one single particle in a Stokes flow
- (x_i, ξ_i) the center and orientation of the i^{th} particle

Control of the minimal distance

Cluster configuration

Proposition

For all $1 \leq i \leq N$ and $j \neq i$ we have

$$\begin{aligned} |\dot{\xi}_i| &\lesssim \|\nabla \mathcal{K}^N \rho^N\|_\infty |\xi_i| + O(d_{\min}), \\ |\dot{x}_+^i - \dot{x}_+^j| &\lesssim \|\nabla \mathcal{K}^N \rho^N\|_\infty |x_+^i - x_+^j| + |\xi_i - \xi_j| + O(d_{\min}), \\ |\dot{\xi}_i - \dot{\xi}_j| &\lesssim \|\nabla \mathcal{K}^N \rho^N\|_\infty |\xi_i - \xi_j| + \|\nabla^2 \mathcal{K}^N \rho^N\|_\infty |x_+^i - x_+^j| + O(d_{\min}). \end{aligned}$$

Proposition

There exists a positive constant $C > 0$ independent of N such that:

$$\|\mathcal{K}^N \rho^N\|_{W^{2,\infty}(\mathbb{R}^3)} \leq C \left(\frac{W_\infty^3}{d_{\min}} + \frac{W_\infty^3}{d_{\min}^2} + \frac{W_\infty^3}{d_{\min}^3} \right) \|\rho\|_{W^{1,\infty}(\mathbb{R}^3) \cap W^{1,1}(\mathbb{R}^3)}.$$

Limitation of the mean-field approach

Cluster configuration

Formally

$$\frac{d}{dt} W_\infty(\rho^N(t, \cdot), \rho(t, \cdot)) \lesssim \|\mathcal{K}^N \rho^N - \mathcal{K} \rho\|_{L^\infty} + \|\nabla \mathcal{K}^N \rho^N - \nabla \mathcal{K} \rho\|_{L^\infty}$$

$$\begin{aligned} \|\mathcal{K}^N \rho^N - \mathcal{K} \rho\|_{L^\infty} &\lesssim \|\rho\|_\infty W_\infty(\rho^N, \rho) \left(1 + \frac{W_\infty(\rho^N, \rho)^2}{d_{\min}} \right) \\ \|\nabla \mathcal{K}^N \rho^N - \nabla \mathcal{K} \rho\|_{L^\infty} &\lesssim \|\rho\|_\infty W_\infty(\rho^N, \rho) \left(|\log W_\infty(\rho^N, \rho)| \right. \\ &\quad \left. + \frac{W_\infty(\rho^N, \rho)^2}{d_{\min}^2} + 1 \right) \end{aligned}$$

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A mesoscopic model for inertialess sedimentation

$(t, x) \mapsto (u(t, x), p(t, x))$ the fluid velocity and pressure.

$(t, x) \mapsto \rho(t, x)$ the (probability) density of the suspension.

$$\left\{ \begin{array}{lcl} \partial_t \rho + \operatorname{div}((u + \kappa g)\rho) & = & 0, \\ -\Delta u + \nabla p & = & 6\pi r_0 \kappa \rho g, \\ \operatorname{div} u & = & 0, \\ u & = & 0, \\ \rho(0, \cdot) & = & \rho_0, \end{array} \right. \begin{array}{l} \text{on } \mathbb{R}^+ \times \mathbb{R}^3, \\ \text{on } \mathbb{R}^+ \times \mathbb{R}^3, \\ \text{on } \mathbb{R}^+ \times \mathbb{R}^3, \\ \text{at infinity} \\ \text{on } \mathbb{R}^3. \end{array} \quad (\text{TS})$$

$\kappa g = \frac{2}{9} r^2 (\rho_p - \rho_f) g$ the velocity fall of one particle given by Stokes law.

$6\pi r_0 \kappa g = n \frac{4}{3} \pi r^3 (\rho_p - \rho_f) g \rho := \lambda (\rho_p - \rho_f) g \rho$ the Brinkman force or the collective force applied by the suspension on the fluid where λ the volume fraction of the suspension.

Experimental and numerical behaviour of falling dispersed particles/droplets in a viscous fluid

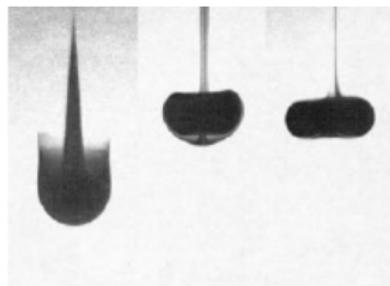


Figure: Droplet breakup and torus formation¹

- G. K. BATCHELOR AND J. M. NITSCHE, *Break-up of a falling drop containing dispersed particles*, J . Fluid Mech. Volume 340, (10 June 1997)
- ¹ G. MACHU, W. MEILE, L. C. NITSCHE, AND U. SCHAFLINGER, *Coalescence, torus formation and breakup of sedimenting drops: experiments and computer simulations*, J . Fluid Mech. Volume 447, (25 November 2001)
- B. METZGER, M. NICOLAS, AND É. GUAZZELLI, *Falling clouds of particles in viscous fluids*, J . Fluid Mech. Volume 580, (10 June 2007), pp. [283,301].

Comparison to the falling of a liquid viscous droplet in a lighter viscous fluid

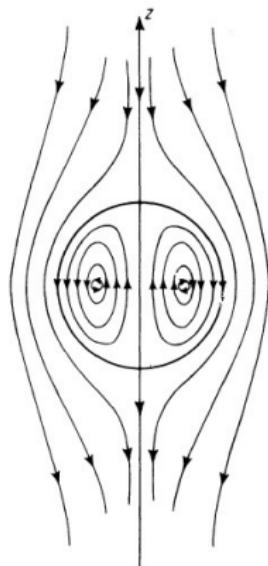


Figure: Streamlines for liquid droplet showing internal circulation¹

Invariance of the spherical shape falling according to a translational velocity given by

$$V = \frac{2}{9\mu} r^2 (\rho_I - \rho) g \frac{\mu_I + \mu}{\mu_I + \frac{2}{3}\mu},$$

μ_I, ρ_I the viscosity and density of the interior liquid in the sphere.

- M. J. HADAMARD, *Mouvement permanent lent d'une sphère liquide et visqueuse dans un liquide visqueux*, C. R. Acad. Sci. 152, (1911)
- ¹ J. HAPPEL AND H. BRENNER Low Reynolds number hydrodynamics. Figure 4-21.1. 1965
- W. RYBCZYNSKI, *Über die fortschreitende bewegung einer flüssigen kugel in einem zähen medium*, Bull. Acad. Sci. Cracovie, (1911)

Analysis of the TS model

Global existence and uniqueness result for regular initial densities can be found in the paper of R. M. Höfer.

Up to a change of variable, we consider the following equation in the following

$$\left\{ \begin{array}{lcl} \partial_t \rho + \operatorname{div}(\rho u) & = & 0, \\ -\Delta u + \nabla p & = & -\rho e_3, \\ \operatorname{div} u & = & 0, \\ u & = & 0, \\ \rho(0, \cdot) & = & \rho_0, \end{array} \right. \begin{array}{l} \text{on } \mathbb{R}^+ \times \mathbb{R}^3, \\ \text{on } \mathbb{R}^+ \times \mathbb{R}^3, \\ \text{on } \mathbb{R}^+ \times \mathbb{R}^3, \\ \text{at infinity} \\ \text{on } \mathbb{R}^3. \end{array} \quad (1)$$

- R. M. HÖFER 2018, R. M. HÖFER AND R. SCHUBERT 2020.

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Theorem (AM 20')

Let $\rho_0 \in L^\infty(\mathbb{R}^3)$ a probability measure with finite first moment. There exists a unique couple $(\rho, u) \in L^\infty(0, T; L^1(\mathbb{R}^3) \cap L^\infty(\mathbb{R}^3)) \times L^\infty(0, T; W^{1,\infty}(\mathbb{R}^3))$ satisfying the transport-Stokes equation (1) for all $T \geq 0$. Moreover, for all $s \in [0, T]$ there exists a unique characteristic flow

$$X(\cdot, s, \cdot) \in L^\infty(0, T, W^{1,\infty}(\mathbb{R}^3))$$

$$\begin{cases} \partial_t X(t, s, x) &= u(s, X(t, s, x)), & \forall t, s \in [0, T], \\ X(s, s, x) &= x, & \forall s \in [0, T], \end{cases}$$

For all $s, t \in [0, T]$ the diffeomorphism $X(s, t, \cdot)$ is measure preserving and we have

$$\rho(t, \cdot) = X(t, 0, \cdot) \# \rho_0.$$

Regularity of the velocity field

Proposition

Let $\eta \in L^\infty(\mathbb{R}^3) \cap L^1(\mathbb{R}^3)$, the unique u solution to the Stokes equation:

$$\begin{cases} -\Delta u + \nabla p = -\eta e_3, & \text{on } \mathbb{R}^3 \\ \operatorname{div}(u) = 0, & \text{on } \mathbb{R}^3, \\ u = 0, & \text{at infinity} \end{cases}$$

is given by $u = -\Phi \star \eta e_3$ with the Oseen tensor Φ

$$\Phi(x) = \frac{1}{8\pi} \left(\frac{\mathbb{I}_3}{|x|} + \frac{x \otimes x}{|x|^3} \right).$$

$u \in W^{1,\infty}(\mathbb{R}^3)$ and there exists a positive constant independent of the data such that:

$$\|u\|_\infty + \|\nabla u\|_\infty \leq C \|\eta\|_{L^1 \cap L^\infty}.$$

Stability estimates using the first Wasserstein distance

For any $\eta_1, \eta_2 \in L^1(\mathbb{R}^3) \cap L^\infty(\mathbb{R}^3)$ and $u_i = -\Phi \star \eta_i e_3$ we have

$$\int_{\mathbb{R}^3} |u_1(x) - u_2(x)| \rho(dx) \leq C(\|\eta_i\|_{L^1 \cap L^\infty}) W_1(\eta_1, \eta_2).$$

For any $u_i \in L^\infty(0, T; W^{1,\infty}(\mathbb{R}^3))$, $i = 1, 2$ and ρ_i the solution to the associated transport equation

$$W_1(\rho_1(t), \rho_2(t))$$

$$\leq \left(W_1(\rho_1(s), \rho_2(s)) + \int_s^t \int_{\mathbb{R}^3} |u_2(\tau, x) - u_1(\tau, x)| \rho_1(\tau, x) dx d\tau \right) e^{Q_2(t-s)},$$

where $Q_i := \|u_i\|_{L^\infty(0, T; W^{1,\infty})}$.

- M. HAURAY AND P. E. JABIN, *Particle approximation of Vlasov equations with singular forces : propagation of chaos*, Ann. Sci. Éc. Norm. Supér. (4), (2015).

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Derivation of an equation for the surface evolution

If $\rho_0 = 1_{B_0}$ then $\rho_t = 1_{B_t}$ where B_t is transported along the flow.

Let consider

$$\partial B_0 = \left\{ r_0(\theta) \begin{pmatrix} \cos(\phi) \sin(\theta) \\ \sin(\phi) \sin(\theta) \\ \cos(\theta) \end{pmatrix}, (\theta, \phi) \in [0, \pi] \times [0, 2\pi] \right\},$$

We set then $c(t) = (0, 0, c_3(t)) \in B_t$ the position at time t of a reference point such that $c(0) = 0$ and write $B_t = c(t) + \tilde{B}_t$ where

$$\partial \tilde{B}_t = \left\{ r(t, \theta) \begin{pmatrix} \cos(\phi) \sin(\theta) \\ \sin(\phi) \sin(\theta) \\ \cos(\theta) \end{pmatrix}, (\theta, \phi) \in [0, \pi] \times [0, 2\pi] \right\}.$$

Derivation of the evolution equation for the surface droplet

$$\begin{cases} \partial_t r + A_1[r] \partial_\theta r &= A_2[r], \quad \text{on } \mathbb{R}^+ \times [0, \pi] \\ r(0, \cdot) &= r_0, \quad \text{on } [0, \pi] \end{cases} \quad (\text{H})$$

In the case where the reference point $c = (0, 0, c_3)$ is transported along the flow i.e. $u(c) = \dot{c}$ we have $c = c[r] = (0, 0, c[r]_3)$ and

$$\begin{cases} \dot{c}[r]_3(t) &= -\frac{1}{4} \int_0^\pi r^2(t, \bar{\theta}) \sin(\bar{\theta}) \left(1 - \frac{1}{2} \sin^2(\bar{\theta}) \right) d\bar{\theta}, \\ c[r]_3(0) &= 0, \end{cases} \quad (\text{C})$$

Remark

The volume of the droplet is conserved in time

$$\int_0^\pi \partial_t r(t, \theta) r^2(t, \theta) \sin(\theta) d\theta = 0.$$

$$A_1[r] = \frac{1}{r}(\mathcal{U}[r] - \dot{c}) \cdot \partial_\theta e(\cdot, 0), \quad A_2[r] = (\mathcal{U}[r] - \dot{c}) \cdot e(\cdot, 0).$$

$$\mathcal{U}[r](\theta) = \int_{(0,\pi) \times (0,2\pi)} \int_0^{r(\bar{\theta})} \Phi(r(\theta)e(\theta, 0) - z e(\bar{\theta}, \bar{\phi})) z^2 \sin(\bar{\theta}) dz d\bar{\theta} d\bar{\phi},$$

$$\begin{aligned} \mathcal{U}[r](\theta) = & -\frac{1}{8\pi} \int_{[0,\pi] \times [0,2\pi]} \left(\frac{(r(\theta)e(\theta, 0) - r(\bar{\theta})e(\bar{\theta}, \bar{\phi})) \cdot e_3}{|r(\theta)e(\theta, 0) - r(\bar{\theta})e(\bar{\theta}, \bar{\phi})|} s[r](\bar{\theta}, \bar{\phi}) \right. \\ & \left. - \frac{(r(t, \theta)e(\theta, 0) - r(\bar{\theta})e(\bar{\theta}, \bar{\phi})) \cdot s[r](\bar{\theta}, \bar{\phi})}{|r(\theta)e(\theta, 0) - r(\bar{\theta})e(\bar{\theta}, \bar{\phi})|} e_3 \right) d\bar{\theta} d\bar{\phi}. \end{aligned}$$

$e(\theta, \phi) \in \mathbb{S}^2$, $s[r](\bar{\theta}, \bar{\phi})$ the surface element on \tilde{B}_t .

$$A_1[r](t, \theta) :=$$

$$-\frac{1}{8\pi r(t, \theta)} \int_0^{2\pi} \int_0^\pi \frac{r(t, \bar{\theta}) \sin(\bar{\theta}) - \partial_\theta r(t, \bar{\theta}) \cos(\bar{\theta})}{\beta[r](t, \theta, \bar{\theta}, \phi)} r(t, \bar{\theta}) \sin(\bar{\theta}) (r(t, \theta) \cos(\phi) \\ - r(t, \bar{\theta}) \left\{ \cos(\bar{\theta}) \cos(\theta) \cos(\phi) + \sin(\bar{\theta}) \sin(\theta) \right\}) d\bar{\theta} d\phi + \frac{\dot{c}_3 \sin(\theta)}{r(t, \theta)}$$

$$A_2[r](t, \theta) :=$$

$$-\frac{1}{8\pi} \int_0^{2\pi} \int_0^\pi \frac{r(t, \bar{\theta}) \sin(\bar{\theta}) - \partial_\theta r(t, \bar{\theta}) \cos(\bar{\theta})}{\beta[r](t, \theta, \bar{\theta}, \phi)} r(t, \bar{\theta}) \sin(\bar{\theta}) (-r(t, \bar{\theta}) \sin(\theta) \cos(\bar{\theta}) \cos(\phi) \\ + r(t, \bar{\theta}) \cos(\theta) \sin(\bar{\theta})) d\bar{\theta} d\phi - \dot{c}_3 \cos(\theta).$$

$$\beta[r](\theta, \bar{\theta}, \phi)^2 = r^2(\theta) + r^2(\bar{\theta}) - 2r(\theta)r(\bar{\theta})(\sin(\theta) \sin(\bar{\theta}) \cos(\phi) + \cos(\theta) \cos(\bar{\theta})).$$

Estimates on the non local operators

We set

$$|r|_* = \inf_{(0,\pi)} r(\theta) > 0.$$

$$\begin{aligned} |\mathcal{U}[r](\theta)| &\leq C \int_{(0,\pi) \times (0,2\pi)} \int_0^{r(\bar{\theta})} \frac{z^2 dz}{|r(\theta)\mathbf{e}(\theta,0) - z\mathbf{e}(\bar{\theta},\bar{\phi})|} \sin(\bar{\theta}) d\bar{\theta} d\bar{\phi}, \\ &\leq \frac{\|r\|_\infty^{5/2}}{\sqrt{|r|_*}} \int_0^{2\pi} \int_0^\pi \frac{\sin(\bar{\theta}) d\bar{\theta} d\bar{\phi}}{|\mathbf{e}(\bar{\theta},\bar{\phi}) - \mathbf{e}(\theta,0)|} \\ \int_0^{2\pi} \int_0^\pi \frac{\sin(\bar{\theta}) d\bar{\theta} d\bar{\phi}}{|\mathbf{e}(\bar{\theta},\bar{\phi}) - \mathbf{e}(\theta,0)|} &= \int_{\partial B(0,1)} \frac{d\sigma(y)}{|y-x|} < C, \forall x \in \partial B(0,1) \end{aligned}$$

bounds and stability estimates

$$\begin{aligned}\|A_1[r]\|_{1,\infty} &\leq K \left(\|r\|_{1,\infty}, \frac{1}{|r|_*} \right) \\ \|A_1[r_1] - A_1[r_2]\|_\infty &\leq K \left(\frac{1}{|r_1|_*}, \frac{1}{|r_2|_*}, \|r_1\|_\infty, \|r_2\|_\infty \right) \|r_1 - r_2\|_\infty\end{aligned}$$

Remark

$$A_1[r](t, 0) = A_1[r](t, \pi) = 0.$$

The characteristic curves are well defined

Local existence and uniqueness

Theorem (AM 20')

Let $r_0 \in \mathcal{C}^{0,1}[0, \pi]$ such that $|r_0|_* > 0$. There exists $T > 0$ and a unique $r \in \mathcal{C}(0, T; \mathcal{C}^{0,1}(0, \pi))$ satisfying the hyperbolic equation (H). Moreover, there exists a unique associated reference point $c = c[r] \in \mathcal{C}(0, T)$ satisfying (C).

Remark

The same result holds true if the motion of the center c is defined in another way. The only properties needed is a uniform bound on \dot{c} and a stability estimate with respect to r if $c = c[r]$.

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Recovering the Hadamard and Rybczynksi result in the spherical case
 $B_0 = B(0, 1)$ means that we should have $B_t = v^*t + B_0$ with v_* the velocity fall of the droplet given by

$$v^* = \frac{2}{9} \frac{R^2}{\mu} (\bar{\rho} - \rho) \frac{\mu + \bar{\mu}}{\bar{\mu} + \frac{2}{3}\mu} g. \quad (2)$$

In particular, we can recover explicitly the following property showed by Hadamard and Rybczynski

Lemma (Hadamard–Rybczynski)

Let $u_0 = -\Phi * 1_{B_0} e_3$, $v^* = -\frac{4}{15} e_3$. We have

$$(u_0 - v^*) \cdot n = 0 \text{ on } \partial B_0$$

Corollary

The solution (u, ρ) of the transport-Stokes equation (1) in the case where $\rho_0 = 1_{B_0}$ is given by

$$u(t, x) = u_0(x - v^*t), \quad \rho(t, x) = \rho_0(x - v^*t), \\ u_0 = -\Phi * \rho_0 e_3, \quad \rho_0 = 1_{B(0,1)}.$$

In other words, the drop B_t remains spherical for all time.

Proof.

$$\partial_t \rho + \nabla \rho \cdot u = (\nabla \rho_0 \cdot (u_0 - v^*))|_{(\cdot - v^*t)} = 0,$$

we conclude using the fact that $\nabla \rho_0 = ns^1$ where s^1 is the surface measure on the sphere and n the unit normal. □

Recovering the spherical shape in the hyperbolic equation $\partial_t r + A_1[r] \partial_\theta r = A_2[r]$

Case 1. We set $c = v^*t$. The result is straightforward.

Proof.

We recall that

$$A_2[r] = (\mathcal{U}[r] - \dot{c}) \cdot e(\cdot, 0)$$

At $t = 0$, $r = r_0 = 1$ and $A_2[1] = (u_0 - v^*) \cdot n = 0$ hence $r_0 = 1$ is solution all the time. □

Case 2. $c \neq v^* t$

Proposition

Let $r_0 = 1$ and (r, c) the solution of (H), with $\dot{c} \neq v^*$. Denote by $T > 0$ the maximal time of existence of the solution such that $|c - c^*| \leq 1$ with $c^* = v^* t = -\frac{4}{15} e_3 t$. Then r is given by

$$r(t, \theta) = -(c - c^*)_3 \cos(\theta) + \sqrt{1 - (c - c^*)_3^2 \sin^2(\theta)}, \quad (t, \theta) \in [0, T] \times [0, \pi]$$

and satisfies

$$|c(t) + r(t, \theta) e(\theta, 0) - v^* t|^2 = 1 \text{ for all } \theta \in [0, \pi] \text{ and } t \leq T.$$

In other words

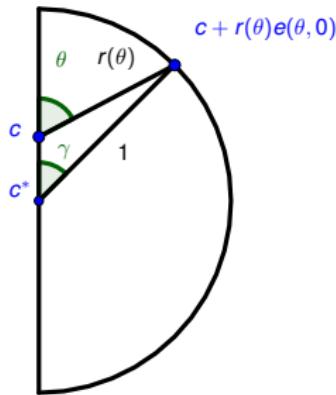
$$\partial B_t := c + \partial \tilde{B}_t = \partial B(c^*, 1) \text{ on } [0, T].$$

Proof.

$$\bar{r}(t, \theta) = -(c - c^*)_3 \cos(\theta) + \sqrt{1 - (c - c^*)_3^2 \sin^2(\theta)}, \quad (t, \theta) \in [0, T] \times [0, \pi]$$

is a solution iff

$$(\dot{c}^* - \mathcal{U}[\bar{r}]) \cdot (\bar{r} e(\theta, 0) + c - c^*) = 0$$



Use the change of variable

$$c + \bar{r}(\theta)e(\theta, 0) - c^* = e(\gamma, 0)$$

and show that

$$\mathcal{U}[\bar{r}](t, \theta) = \mathcal{U}[1](\gamma)$$



Global existence in the spherical case

We assume that c is transported along the flow

$$\begin{cases} \dot{c}[r]_3(t) &= -\frac{1}{4} \int_0^\pi r^2(t, \bar{\theta}) \sin(\bar{\theta}) \left(1 - \frac{1}{2} \sin^2(\bar{\theta}) \right) d\bar{\theta}, \\ c[r]_3(0) &= 0, \end{cases} \quad (\text{C})$$

Proposition

Let $r_0 = 1$ and (r, c) the solution of (H) and (C). For all time $t \geq 0$ we have $c_3(t) \leq c_3^*(t)$, $|c(t) - c^*(t)| \leq 1$ and

$$\lim_{t \rightarrow \infty} c_3(t) - c_3^*(t) = -1$$

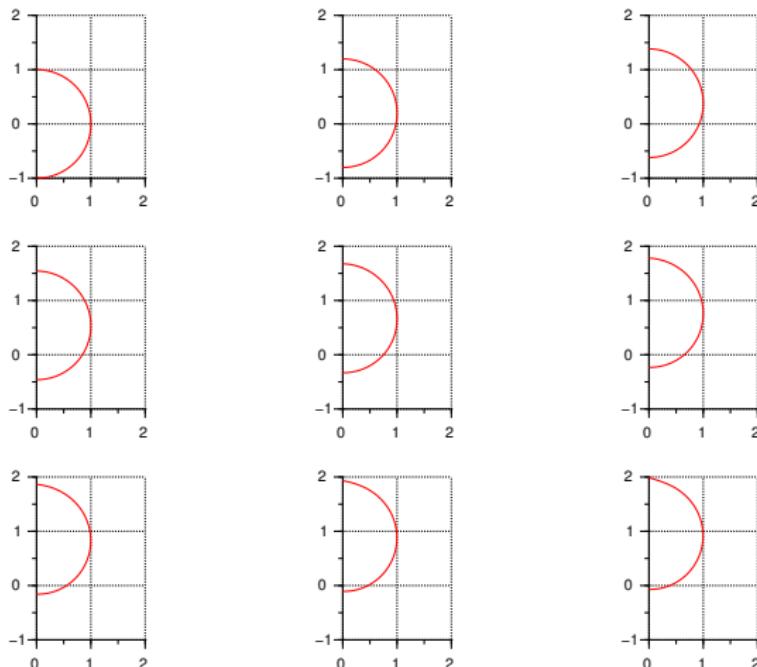


Figure: Droplet evolution for $t = 0, 3, \dots, 24$

Numerical simulation using upwind finite difference scheme

Numerical investigation of a special case

We choose $\dot{c} = \lambda \dot{c}^*$ with $\lambda > 1$. We have

$$|c(t) - c^*(t)| = t(\lambda - 1)|v^*| = t(\lambda - 1)\frac{4}{15},$$

if we set for instance $\lambda = \frac{17}{2}$, the time \bar{t} for which one should have $|c(\bar{t}) - c^*(\bar{t})| = 1$ is $\bar{t} = 0.5$.

t	0	0.1	0.2	0.3	0.35	0.4	0.45	0.49	0.5
$ c - c^* $	0.02	0.22	0.42	0.62	0.72	0.82	0.92	1.00	1.02
$E_1^n (\times 10^{-2})$	0.02	0.22	0.48	0.83	1.08	1.4	1.86	2.51	2.82
$\min_i r_i^n$	0.98	0.78	0.58	0.38	0.28	0.1805	0.0807	0.0009	-0.1394
$V^n (\times 10^{-2})$	0.03	0.436	0.87	1.38	1.68	2.014	2.42	2.84	-

Table: Second test case. Evolution of E_1^n , $\min_i r_i^n$ and V^n

Ongoing work

- Investigation of an appropriate scheme for the hyperbolic equation (convergence result and stability, ensuring the steady state approximation?)
- Investigation of other axisymmetric shapes such as ellipsoids

$$r_0(\theta) = \frac{1}{\sqrt{1 - \frac{3}{4} \cos^2(\theta)}}, \quad r_0(\theta) = \frac{1}{\sqrt{1 - \frac{3}{4} \sin^2(\theta)}}, \quad \theta \in [0, \pi],$$

“Simulation” of an ellipse case

